

# THI SAFETY SYSTEM

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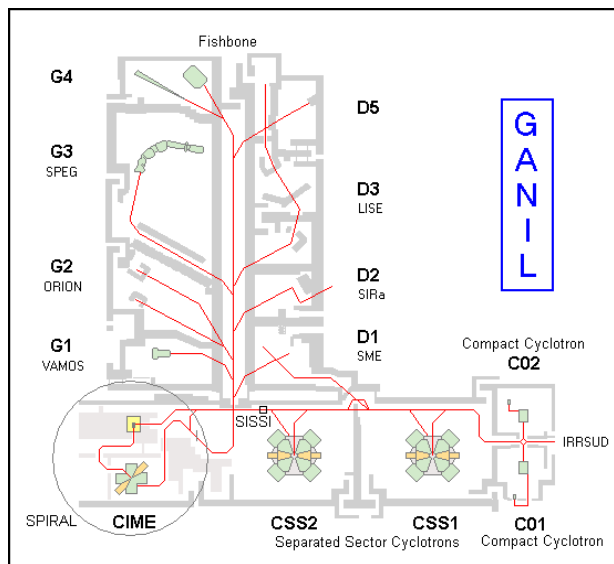
## Abstract

For several years, GANIL has been allowed to reach a maximum beam power of six kilowatts (400W in normal mode) thanks to the THI system (High Intensity Transport System). Three modes of running are necessary to accelerate a THI beam ("Injector" mode, "tuning" mode and "surveillance" mode). The "surveillance" mode requires a safety system to protect equipment against beam losses. Inside cyclotrons, diagnostics measure beam-loss currents at the injection and extraction devices. Along beam lines, diaphragms measure beam-loss currents at the input and output of dipoles. Current transformers are used for beam transmission measurements through beam lines and the cyclotrons. The safety system controls beam losses and quickly cuts the beam with a chopper if losses exceed thresholds. These thresholds can be seen and changed by software.

## INTRODUCTION

The production of exotic ions at GANIL is performed by fragmentation of the projectile in the target of SISSI [5] or/and by the ISOL method with an acceleration of the exotic beams by the cyclotron CIME [3].

### Layout of GANIL



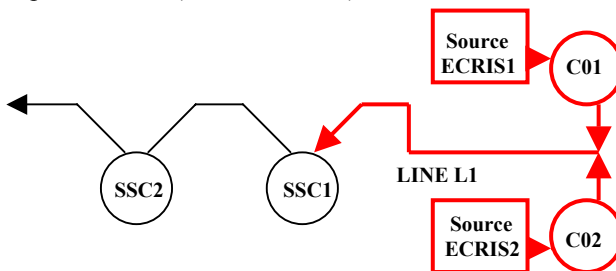
Both devices require high intensity primary beams. Primary beam intensity has been increased up to  $15\mu\text{Ae}$  (3kW) for  $^{13}\text{C}$  at 95MeV/A and  $26\mu\text{Ae}$  (5kW) for  $^{36}\text{Ar}$  at 95MeV/A. Therefore, uncooled or unshielded elements can melt very rapidly and must be protected by a safety system.

## THI MODES

Three modes of running are necessary to tune a THI beam. C01 or C02 can be chosen to post accelerate the THI beam.

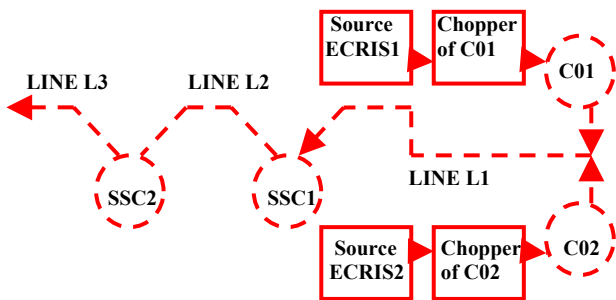
### “Injector mode”

This mode permits us to accelerate the beam at the input of SSC1. ( $P_{\text{beam}} < 400\text{W}$ )



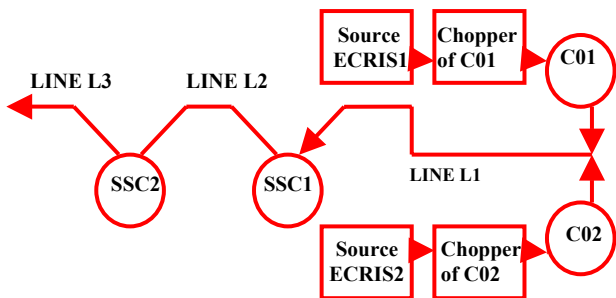
### “Tuning mode”

This mode permits us to tune the beam through the accelerators. Beam chopping rates limit the beam power ( $P_{\text{beam}} < 400\text{W}$ )



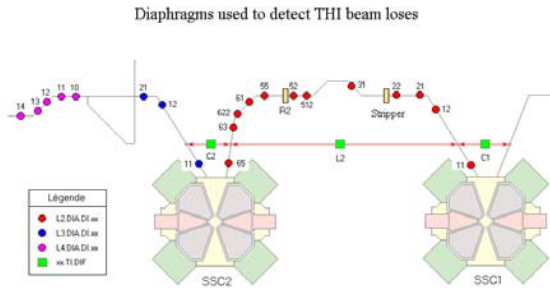
### “Surveillance mode”

This mode permits us to tune the beam at a maximum power ( $P_{\text{beam max}} = 6\text{kW}$ ). Beam current average is increased progressively by changing beam-chopping rates. The safety system controls beam losses.

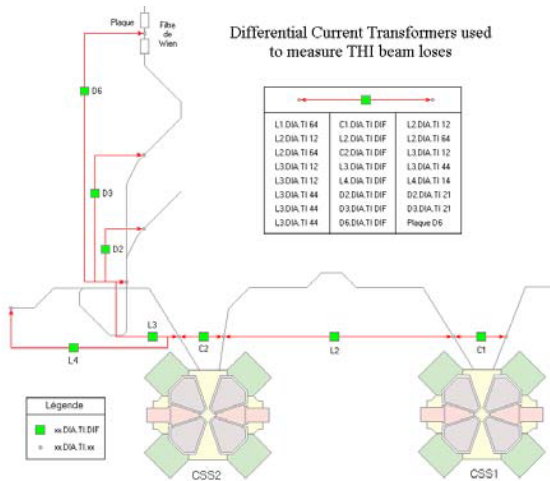


## BEAM LOSSES DIAGNOSTICS

Inside cyclotrons, diagnostics measure beam-loss currents at the input of the injection and extraction. Along beam lines, diaphragms detect beam-loss currents at the input and output of dipoles.



Current transformers (GANIL ACCT) are used to measure the beam transmission through beam lines and the cyclotrons. A change of the efficiency within the accelerators can be detected. The beam is modulated to measure beam currents with the ACCT. The maximum chopping rate is 91%.



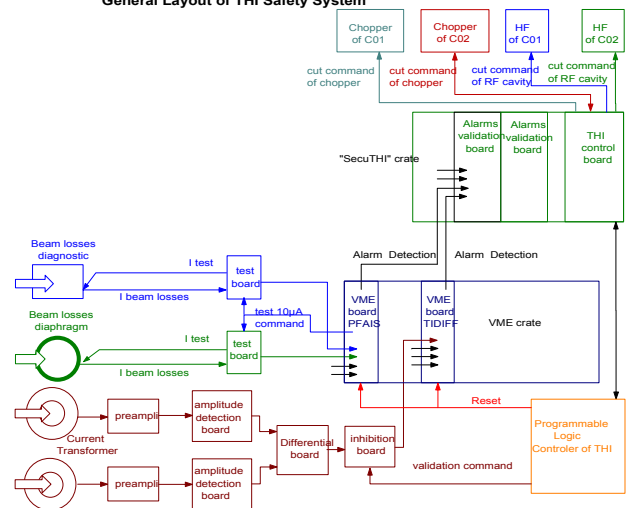
## SAFETY SYSTEM

Interceptive beam diagnostics are connected to test boards. Each board is able to inject a test signal (10µA) to the diagnostics and filter the signal from the device. Test signals can be sent by software. Each VME board (PFAIS) measures 4 diagnostic currents with logarithmic I/V converters, which generate a voltage proportional to the logarithm of the current. This voltage is digitised, compared to a threshold and numerically converted into a current.

The signals generated by the current transformers (ACCT) are sent to a differential board. An inhibition board validates the difference between 2 current transformers. Then a VME board digitises, compares to a threshold and numerically converts into a current.

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## General Layout of THI Safety System

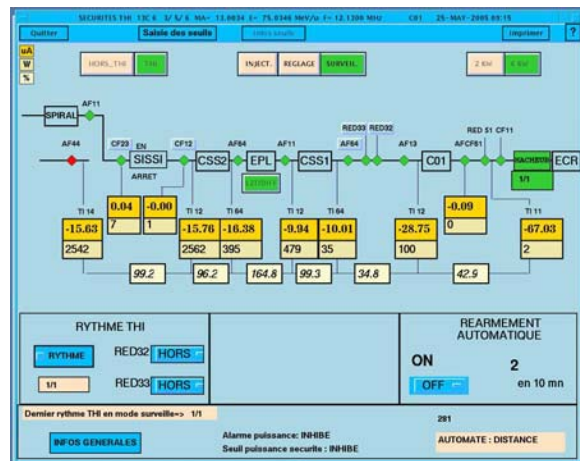


“Alarm detection” signals are generated by VME boards and sent to “alarm validation” boards. “THI control” board collects all alarm signals. A programmable logic controller indicates to the control board different configuration states. If “surveillance” mode is validated for example, when a VME board generates an alarm detection, the THI control board commands the chopper to cut the beam. If a problem is detected on the chopper, the acceleration voltage of the C0 injector is cut.

A reloading system gives us the possibility to restore the beam just after an overshoot. When 3 trigger actions arrive in under 10 seconds, the programmable logic controller passes from “surveillance “ mode to “tuning” mode.

## CONTROL

Software is used to control and tune the beam.



Users can choose various modes of running (normal mode or THI mode and injector, tuning, surveillance mode). Beam current (µA), beam power (W) and efficiency (%) are displayed on the screen. Beam chopping rates can be changed (rythme) and pepper pots inserted in the lines (red32 and red33).

A second program enables us to control and change thresholds of each diagnostic device.

### PHOTOS OF DIAGNOSTICS

SEUILS THI 48Ca20 8/17/18 HA- 47.9525 E- 29.8447 MeV/u I- 7.8220 MHz C01 18-DEC-2003 15:41										
Quitter	Init	Seuils	Seuils en intensite	Fonction sur seuils		Infos seuils	Test deplacement			Imprimer ?
Diagnostic	Pseuil	Diagnostic	Pseuil	Diagnostic	Pseuil	Diagnostic	Pseuil	Diagnostic	Pseuil	
C1.DIA.EI.PHO	5.7 W	L3.DIA.D111.J	5.7 W	C2.DIA.EI.ID	5.0 W	L3.DIA.D111.J	23.8 W	L4.DIA.D110.J	23.8 W	
C1.DIA.EI.IVE	5.7 W	L3.DIA.D121.J	5.7 W	C2.DIA.EI.JG	5.0 W	L3.DIA.D121.J	23.8 W	L4.DIA.D111.J	23.8 W	
C1.DIA.M2.PHO	5.7 W	L3.DIA.D011.J	8.8 W	C2.DIA.EI.IB	5.0 W	L3.DIA.D011.J	23.8 W	L4.DIA.D121.J	23.8 W	
C1.DIA.M2.IVE	5.7 W	L3.DIA.D021.J	56.8 W	C2.DIA.EI.H	5.0 W	L3.DIA.TD1F.J	46.4 W	L4.DIA.D131.J	23.8 W	
C1.DIA.M3.J	5.7 W	L3.DIA.D011.J	5.0 W	C2.DIA.M2.ID	5.0 W	L3.DIA.TD1.J	47.6 W	L4.DIA.D141.J	23.8 W	
C1.DIA.M3.I	5.7 W	L3.DIA.D021.J	15.0 W	C2.DIA.M2.JG	5.0 W	L3.DIA.D011.J	23.8 W	L4.DIA.TD1F.J	96.7 W	
C1.DIA.EE1	28.4 W	L3.DIA.D121.J	5.0 W	C2.DIA.M2.IB	5.0 W	L3.DIA.DH1.J	23.8 W			
C1.DIA.ME2.J	5.7 W	L3.DIA.D051.J	5.0 W	C2.DIA.M2.H	5.0 W	L3.DIA.DH41.J	23.8 W			
C1.DIA.ME3.J	5.7 W	L3.DIA.D061.J	5.0 W	C2.DIA.M2.P	5.0 W			AR.DIA.D011.J	23.8 W	
C1.DIA.ME3.PHO	5.7 W	L3.DIA.D0221.J	5.0 W	C2.DIA.M3.ID	5.0 W			D0.DIA.TD1F.J	47.6 W	
C1.DIA.ME3.IVE	5.7 W	L3.DIA.D031.J	5.0 W	C2.DIA.M3.JG	5.0 W			D0.DIA.D111.J	23.8 W	
C1.DIA.TD1F.J	56.8 W	L3.DIA.D051.J	5.0 W	C2.DIA.M3.IB	5.0 W			D0.DIA.D121.J	23.8 W	
		L3.DIA.TD1F.J	96.1 W	C2.DIA.M3.IB	5.0 W			D0.DIA.D011.J	23.8 W	
				C2.DIA.M3.P	5.0 W			D0.DIA.TD1F.J	47.6 W	
				C2.DIA.M3.IPB	5.0 W			D6.DIA.TD1F.J	47.6 W	
				C2.DIA.M3.ID	5.0 W					
				C2.DIA.M3.JG	5.0 W					
				C2.DIA.M3.IB	5.0 W					
				C2.DIA.M3.H	5.0 W					
				C2.DIA.M3.P	5.0 W					
				C2.DIA.M3.IPB	5.0 W					
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