

OPERATIONAL EXPERIENCE WITH THE PEP-II TRANSVERSE COUPLED-BUNCH FEEDBACK SYSTEMS*

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Abstract

Operational experience with the PEP-II high energy ring (HER) and low energy ring (LER) transverse coupled-bunch feedback systems is discussed. In particular, some key performance data including beam transfer function, mode spectrum, and some growth rate observations are presented. In general, growth rates much greater than expected have been observed in the HER. LER growth rates have not been measured but are thought to be lower than those of the HER based on lower feedback gains required for LER beam stabilization. Some results from experiments using the longitudinal feedback system electronics in conjunction with the transverse feedback system to study the HER instabilities are presented.

1 INTRODUCTION

The PEP-II B-Factory [1] is a high-luminosity, asymmetric electron-positron collider consisting of a 9 GeV, 1.0 A high-energy electron storage ring (HER), and a 3.1 GeV, 2.14 A low-energy positron storage ring (LER). Because of the high average beam currents in both rings, active feedback systems [2] are used to suppress the growth of transverse coupled-bunch instabilities.

During the past year, PEP-II has completed several very successful commissioning periods, the most recent being the Jan/Feb 1999 run during which both rings achieved substantial currents (>500 mA HER and >1100 mA LER) and significant luminosity (5×10^{32}) was obtained [3]. At these high currents, the transverse feedback systems played a critical role in beam containment and stabilization.

In general, the HER has been observed to be less stable than the LER. Typical HER transverse instability thresholds are on the order of ten milliamps while LER thresholds are in the 100 mA area. Feedback gains required to stabilize the two beams roughly reflect the order of magnitude difference in thresholds. Growth rates four-to-ten times greater than expected for the HER have been measured [2]. LER growth rates have not been measured but will be during the next run. Experience thus far with the LER points towards transverse growth rates more in line with predicted rates (table 1). Many

experiments and a great deal of data has been taken to try to determine the origin of the HER instabilities. Work towards a conclusion in this area is ongoing and will be published at a future date.

2 PARAMETER AND SYSTEM REVIEW

A brief list of accelerator and transverse feedback system design parameters appears in Table 1. Nominally, PEP-II operates with every other bucket filled (238 MHz bunch rate). This sets the minimum bandwidth for the feedback system at 119 MHz. However, the electronics has been designed to have a bandwidth of 250 MHz to allow for possible operation with every bucket filled. The kickers cover DC-119 MHz for maximum shunt impedance in the every-other-bucket operating mode. They can be replaced with 238 MHz versions if an every-bucket fill becomes a likely operating mode. The feedback systems are designed to provide a damping rate that is approximately three times greater than the growth rate of the fastest expected (vertical resistive wall) coupled-bunch mode.

Table 1: Accelerator / feedback design parameters.

Parameter	Description	HER / LER Value
E	Beam energy	9.0 / 3.1 GeV
f_{rf}	RF frequency	476 MHz
–	Bucket space	2.1 ns
–	Bunch space	4.2 ns
I_{av}	Average current	1.0 / 2.14 A
f_0	Orbit frequency	136.3 kHz
ν_v	Vertical tune	23.64 / 34.64
ν_h	Horizontal tune	24.57 / 36.57
α_v	Vertical R-wall growth rate (calc)	0.26 / 1.09 ms^{-1}
α_h	Horizontal R-wall growth rate (calc)	0.18 / 0.71 ms^{-1}
α_f	Feedback design damping rate	3.2 ms^{-1}
	Required feedback bandpass	13.6 kHz-119 MHz
	Feedback electronic bandpass	10 kHz-250 MHz
	Kicker bandpass	DC - 119 MHz

The feedback system diagram is shown in figure 1. Beam moment signals ($I\Delta x$) from two sets of pickups are detected with microwave receivers at $3f_{rf}$. After down-conversion to baseband, the signals are proportionately summed to produce a correction signal that is 90 degrees

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out of phase with beam position at the kickers. A digital delay provides the pickup-to-kicker timing and the kicker electrodes are individually driven differentially with 120 W class-A power amplifiers. Other system features include a provision for single-bunch kickout, pre-digitization orbit-offset-rejection electronics, and fast switches to gate the feedback on/off for grow damp measurements with the longitudinal feedback system front-end.

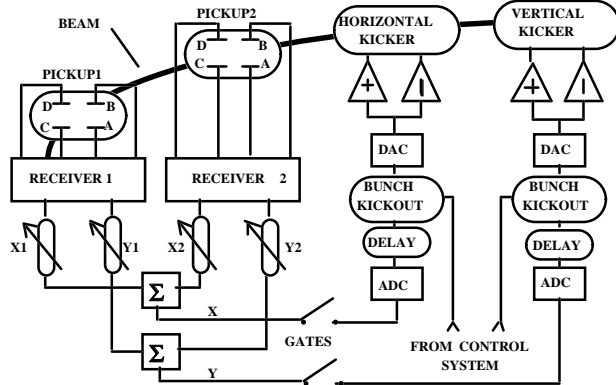


Figure 1: Transverse feedback system.

2 LER OPERATION

Commissioning of the LER began in July, 1998. Experience gained with the HER feedback system made the LER system commissioning a simple and straight forward task. The system was quickly timed using the simple technique described in reference [2]. For rough phasing, the signs of the signals from each of the two pickups were simply set for stability without measuring transfer phase. The system performed well in this rough configuration and was subsequently left alone to make way for other commissioning tasks.

At the beginning of the Jan/Feb 99 run, the LER system was properly phased using a network analyzer in anticipation of going to higher currents. An example vertical transfer function for the properly tuned system appears in figure 2. In this configuration, the system stabilized the beam to the highest currents to date, >1100 mA.

Because of the early success, only limited time was allotted to LER coupled-bunch mode studies. Despite the limited experimental time, some important stability observations were made for the LER. In particular, the beam was found to be less stable in the horizontal plane. This is contrary to theory which indicates that the strongest expected source of instability is the vertical resistive wall impedance. The threshold for horizontal instability is in the 100 mA region. The vertical threshold was not measured but appears to be much higher. The effect of horizontal feedback on the LER beam at 100 mA is shown over the first ten orbit harmonics in figures 3 and

4. In general, the strongest unstable modes appeared at frequencies below 3 or 4 MHz indicating horizontal resistive wall as a possible source. More detailed measurements for the LER including modal growth rates are planned for the next run beginning May 99.

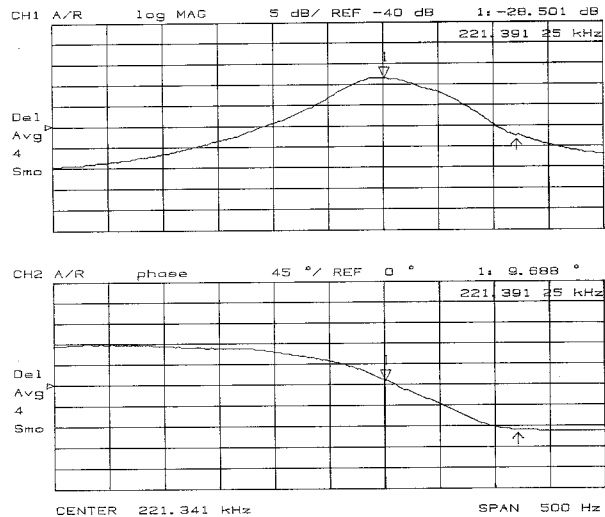


Figure 2: Transfer function of lower vertical sideband of second orbit harmonic (LER).

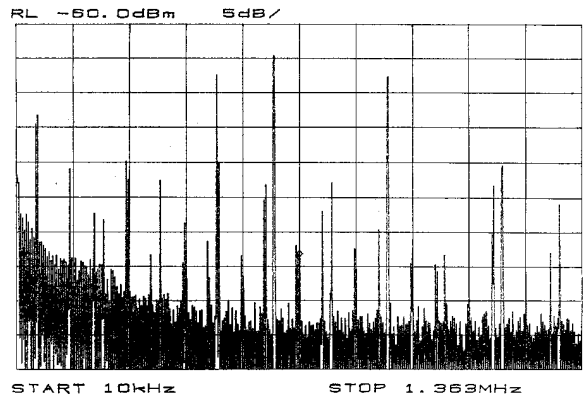


Figure 3: Spectrum of horizontal sidebands about first ten orbit harmonics, feedback off (LER, 100 mA).

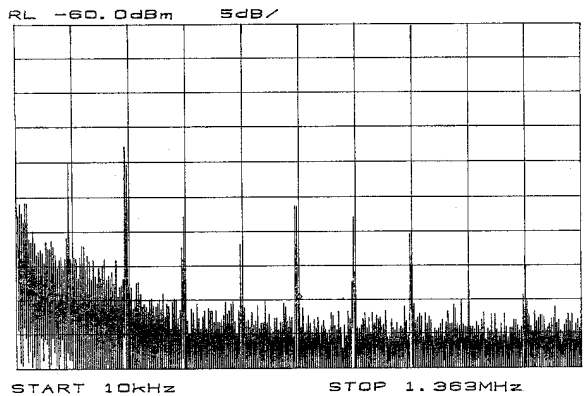


Figure 4: LER spectrum about first ten orbit harmonics with horizontal feedback on, 100 ma.

3 HER OPERATION

During the past several commissioning periods, efforts have been focused on finding the source of the fast HER instabilities [4,5]. Some brief comments on measurement techniques and initial observations are discussed here.

The measurement technique uses one of the longitudinal feedback systems to gate the transverse feedback system off and on with broadband GaAs FET T-section switches allowing beam motion to grow then damp. Bunch-by-bunch transverse motion from the transverse receivers during the grow/damp is recorded and processed with the longitudinal feedback system front-end and DSP farm. With off-line analysis, modal growth/damping rates, closed-loop feedback system behavior, and beam impedance information can be obtained.

An example measurement using this technique for the horizontal plane of the HER is shown in figures 5 and 6 for a 290 bunch, 40 mA beam. Figure 5 shows bunch-by-bunch growth and damping as a function of time. Using Fourier transform techniques, the modal structure of the beam vs. time can be obtained as shown in figure 6. In this case, two low-frequency modes are clearly present. Also note that the growth is non-exponential and that for one mode, the beam decays with feedback to a steady state level. Although not measured here, the growth rates are known to be large and amplitude dependent with the fastest rates occurring for small amplitudes. Thus one explanation for the residual level is that the mode grows to an amplitude (with decreasing growth rate) to where it is marginally controlled by the feedback system gain.

One consequence of extremely high growth rates is that correspondingly high feedback gains are required to stabilize the beam. At these high gains, the system is extremely sensitive to residual orbit-offset signal saturation effects. Efforts to reduce residual orbit-offset signal levels even further are presently underway.

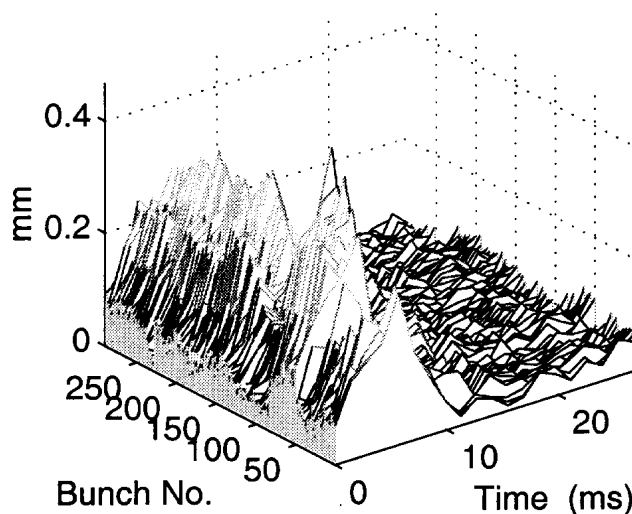


Figure 5: HER horizontal time domain bunch-by-bunch oscillation envelopes, $I_{av} = 40$ mA, 290 bunches.

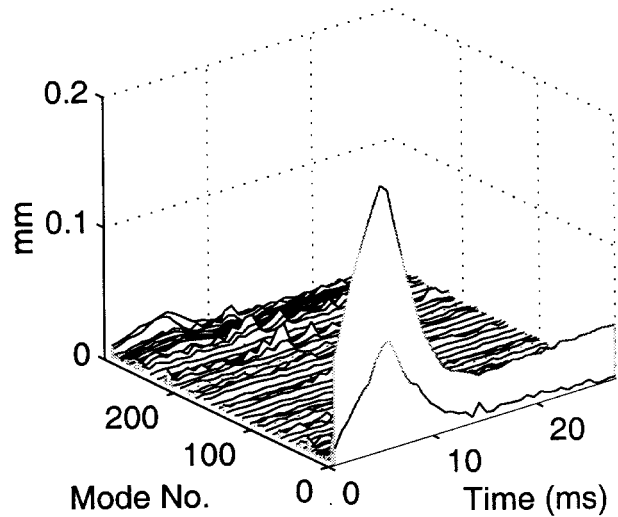


Figure 6: HER time evolution of horizontal modes, $I_{av} = 40$ mA, 290 bunches.

4 CONCLUSION

Both the HER and LER transverse coupled-bunch feedback systems are operational and in use for controlling instabilities in both rings. Observations thus far indicate that the LER is generally well behaved with unstable modes easily controlled by the feedback system. Instabilities in the HER, although basically controlled by the feedback system, are more severe with growth rates much greater than expected. During the next run, HER stability studies will continue, growth rates in the LER will be measured, orbit offset rejection will be improved, and the single-bunch kickout feature for both systems will be tested.

5 REFERENCES

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